## TANTA UNIVERSITY FACULTY OF COMPUTERS AND INFORMATICS



**EXAMINATION FOR (LEVEL 4)** 

COURSE TITLE: CLOUD COMPUTING NETWORKS

COURSE CODE: IT425

TANAN UNIVERSITY

DATE:11/1/2023

**TOTAL MARKS: 60** 

PAGES: 2 TIME ALLOWED: 2HOUR

## Q1) choose the correct answers

1- Which of the fo	ollowing is an open-s	source vii	rtualization	technology		
a) Hyper-V	b) KVM	c) vSphe	ere	d) Fusion Co	ompute	
2- laaS in cloud co	omputing refers to -					
a) Information as a Service		b) Infrastructure as a Service				
c) Industry as a Service		d) Instruction as a Service				
3- On HUAWEI (	CLOUD, a user has	applied f	or an ECS t	hat has only	the operating system	
installed. This	servicer. mode is ( ).	(Single a	nswer)			
a) laaS	b) PaaS	c) SaaS		d) NaaS		
4- Which of the fo	ollowing is true abou	it the typ	e II (hosted)	) virtualizati	ion?	
a) VMM runs on th	e host OS.	b) VMM	I directly rur	ns on the hos	t machine.	
c) VMM runs on the guest OS.		d) VMM runs on the guest machine				
5- If a VM on a pl	hysical host is faulty	, other V	Ms on the p	hysical host	are not affected.	
Which of the fo	ollowing feature of t	he virtual	lization tech	mology is re	flected by the preceding	
description? (si	ingle answer)					
a) Partition	b) Isolation	c)	) Encapsulat	ion	d) Independence	
6- Which of the fo	ollowing is not a Kei	rnel-based	d Virtual M	achine (KV	M) management tool?	
a) Libvirt. b) Virsh command set.		set.	c) Virt	-Manager.	d) QEMU.	
7is an exa	mple of cloud comp	uting 3				
a)docker	)docker b) virtualizations		c)Xen		d) KVM	
8- SAAS allows us	sers to access the					
a)hardware	b)software		c)OS		d) all	
9 runs	directly on the hos	t hardwa	re.			
a) Type1 virtualiza	ation 2) typ	e2		3)KVM	4)all	
10-Which of the fo	ollowing is not a sna	pshot ma	nagement o	ption?		
A. Create a snapsho	bt B. Modify a s	napshot	C. Resto	re a VM usir	ng one of its snapshots	
Q2) Choose true(	T) or false(F) for t	the follov	<u>wing</u>			
1- Cloud computi	ng includes parallel	and distr	ributed com	puting tech	nology	

1-	Cloud computing includes parallel and distributed computing technology
2-	All open-source virtualization technologies are type 1 virtualization, while all
	closed-source ones are type 2 virtualization.
3-	laaS in cloud computing refers to Information as a Service
4-	in precopy technique, first transfers all memory pages, and then only copies

modified pages during the last round iteratively

- 5- virtualization and non-virtualization resources cannot coexist in one data center
- 6- Generally, a VM has a configuration file that records the specifications and name of the VM.
- 7- Multiple VMs running with different OSes can be deployed on the same physical node
- 8- OS-level virtualization creates isolated containers on a single physical server
- 9- The main reason for the rapid development of virtualization is that the VM outperforms the physical machine and has a wider application scope.
- 10-Templates can be used to quickly deploy VMs. At present, templates can be created only by converting or cloning VMs.

## Q3) Answer the following questions

- 1- State three advantages of VLAN
- 2- State when you should use the access link of VLAN and when you should use the trunk link
- 3- What is Hypervisor in Cloud Computing and its types?
- 4- Describe the four characteristics of the virtualization
- 5- What is the difference between pre-copy and post copy memory migration?
- 6- Draw the architecture of Xen VMM.
- 7- How virtual cluster can implement load balancing?
- 8- State 3 different ways to implement memory overcommitment?
- 9- Can you implement instructions from various processors on one physical machine? If yes explain how?
- 10-What is the differenc between SAN and NAS storages?

Good luck Dr. Aida Nasr

$\mathbf{Q}_{\mathbf{I}}$	(1) Complete the following sentences						
1-	is the name of information sent from robot sensors to robot						
	controllers						
2-	Universal joints haveDOF while prismatic joints haveDOF and						
	constraints						
3-	is important for defining the possible positions and orientations a robot can						
	reach						
4-	In ant colony algorithm, if the number of ants the performance of the algorithm						
	increases.						
5-	algorithm is used for finding a robot shortest path						
6-	Robots can explor surrounding environment usingwhile they can change						
	on it using						
7-	is a temperature sensor whileis a light sensor						
8-	- If the robot has 3 gears A, B, and C. The motor is connected to gear A. as shown in the						
	figure, the speed of gear C will be						
	A BUNNER OF OF OF STANDERS OF						
9-	Designers can use for decreasing mobile robot oscillation.						
10-	-Micro-scale robots use as actuator						

Q2) What is the difference between robot and robotics?

Q3)what is the differnec between Locomotion and Manibulation ?	
Q4) give exambles of internal and external sensors	
Q5) give exambles of 3 types of actuators	